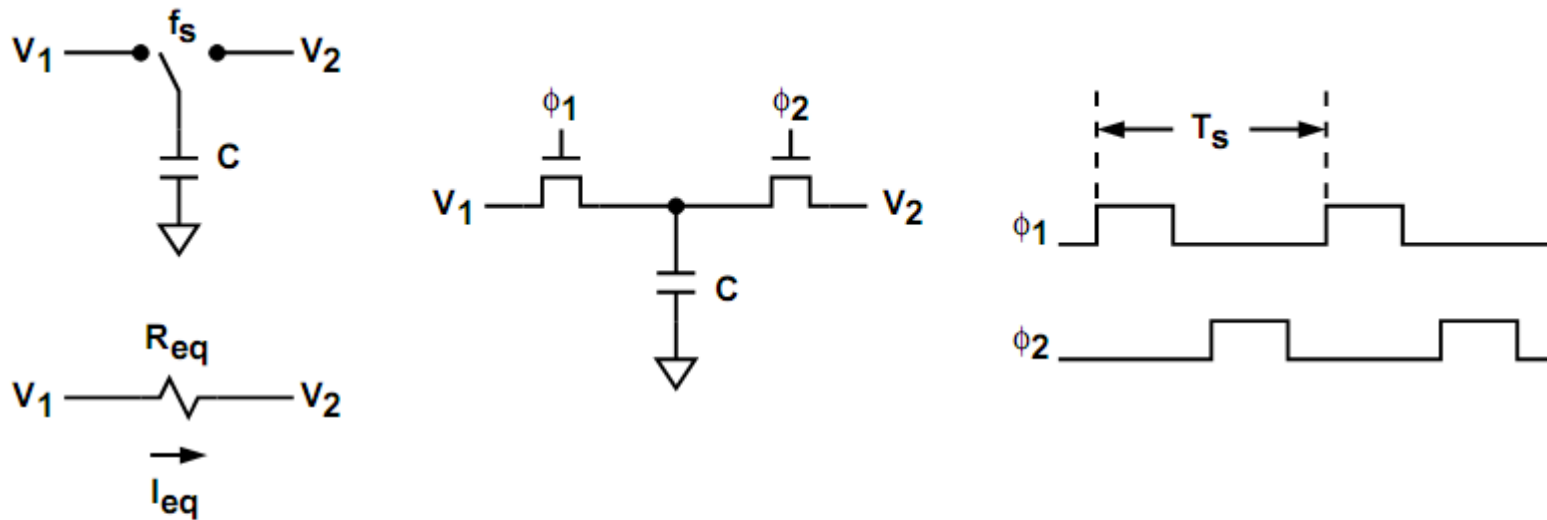


# Switched-capacitor (SC) filters

## ► SC resistor

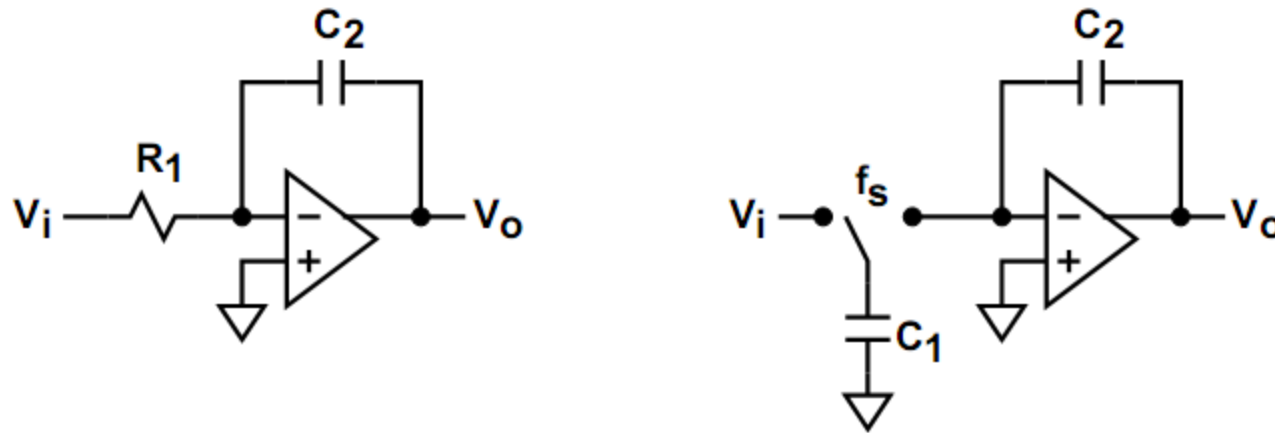


$$I_{eq} = \overline{\left( \frac{\Delta Q}{\Delta t} \right)} = \frac{C \cdot V_1 - C \cdot V_2}{T_s} = C \cdot (V_1 - V_2) \cdot f_s \quad T_s = \frac{1}{f_s}$$

$$G_{eq} = \frac{1}{R_{eq}} = \frac{I_{eq}}{V_1 - V_2} = C \cdot f_s$$

# SC integrator

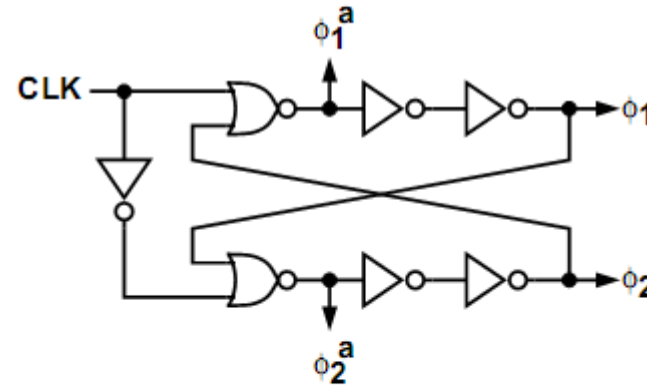
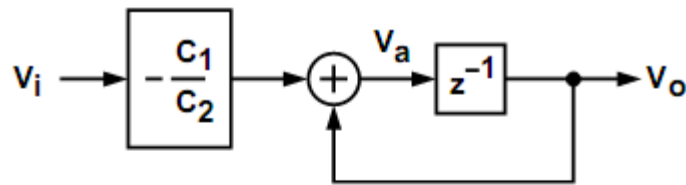
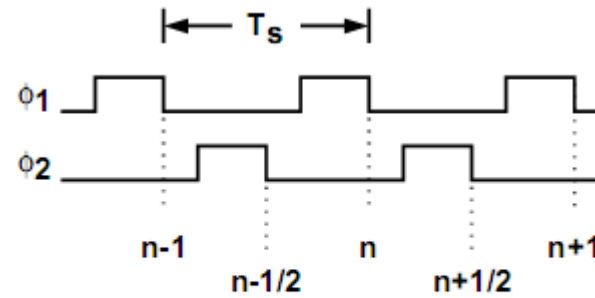
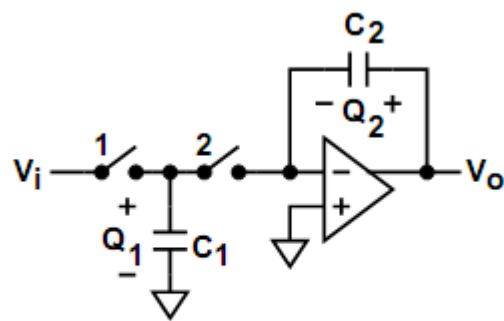
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$$\frac{V_o}{V_i} = -\frac{1}{sR_1C_2} = -\frac{1}{s} \cdot \frac{G_{eq1}}{C_2} = -\frac{1}{s} \cdot \left( f_s \cdot \frac{C_1}{C_2} \right)$$

- Consist of analog switches, capacitors and opamps.
- Discrete-time (or sampled-data) analog filters.
- Time constant is determined by capacitance ratio and switching frequency.

# SC integrator analysis



$$\frac{V_o(z)}{V_i(z)} = -\frac{C_1}{C_2} \times \frac{z^{-1}}{1 - z^{-1}}$$

# SC integrator analysis

---

At cycle  $n$ , i.e.,  $t = nT_s$ , we have  $Q_1(n) = C_1V_i(n)$  and  $Q_2(n) = C_2V_o(n)$

At cycle  $n + 1/2$ , i.e.,  $t = (n + 1/2)T_s$ ,

$$Q_1(n + 1/2) = 0 \quad Q_2(n + 1/2) = Q_2(n) - Q_1(n) = C_2V_o(n) - C_1V_i(n)$$

At cycle  $n + 1$ , i.e.,  $t = (n + 1)T_s$ ,

$$Q_1(n + 1) = C_1V_i(n + 1) \quad Q_2(n + 1) = C_2V_o(n + 1) = Q_2(n + 1/2) = C_2V_o(n) - C_1V_i(n)$$

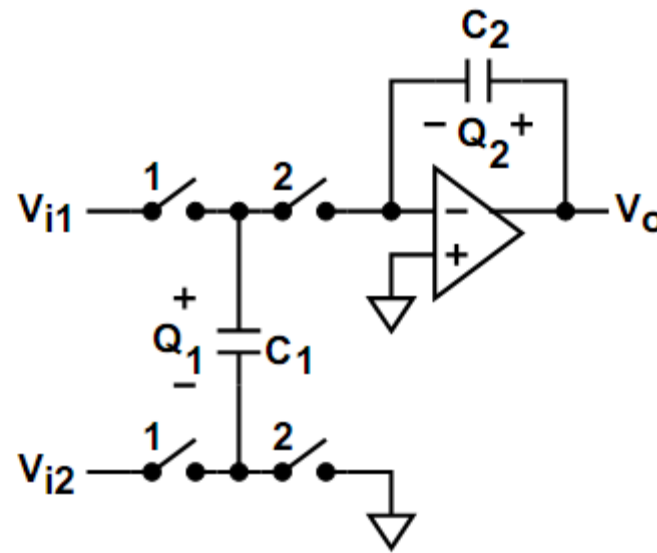
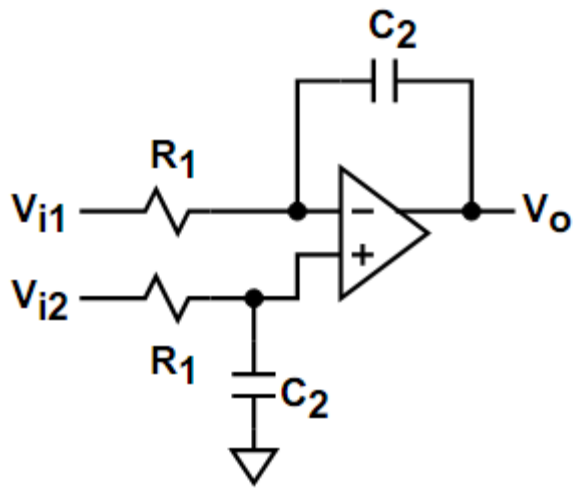
Thus, the time-domain difference equation is

$$C_2V_o(n + 1) = C_2V_o(n) - C_1V_i(n)$$

In the z-domain

$$zC_2V_o(z) = C_2V_o(z) - C_1V_i(z) \quad \Rightarrow \quad \frac{V_o(z)}{V_i(z)} = -\frac{C_1}{C_2} \times \frac{1}{z-1} = -\frac{C_1}{C_2} \times \frac{z^{-1}}{1-z^{-1}}$$

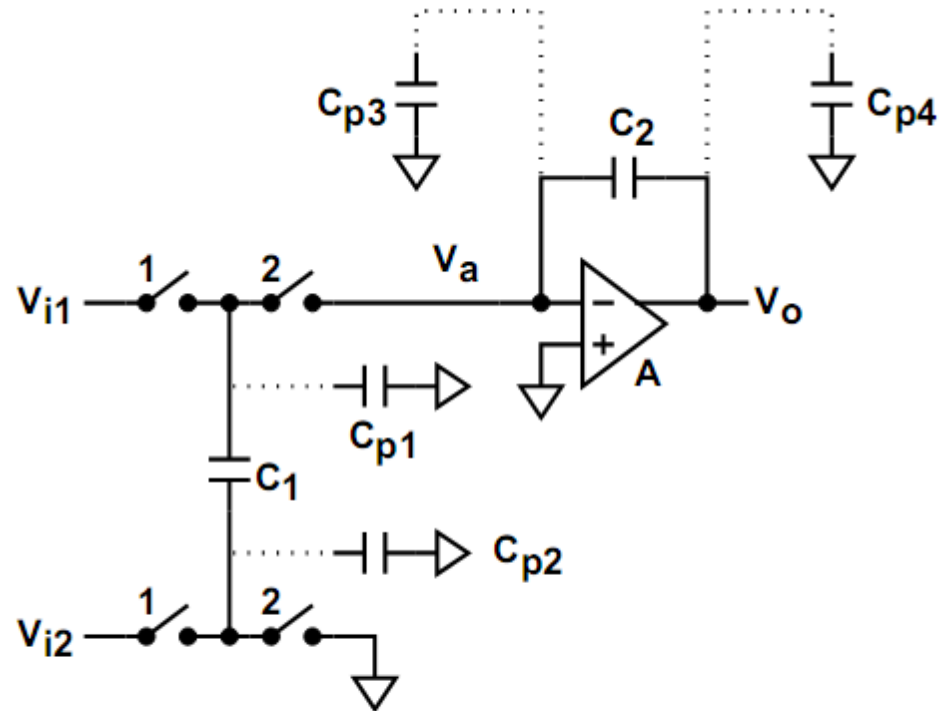
# SC differential integrator



RC Integrator  $\rightarrow V_o(s) = -\frac{1}{sR_1C_2}(V_{i1} - V_{i2})$

SC Integrator  $\rightarrow V_o(z) = -\frac{C_1}{C_2} \times \frac{z^{-1}}{1 - z^{-1}} \times [V_{i1}(z) - V_{i2}(z)]$

# Effects of parasitic Cs



$$V_o(z) = \left[ -\frac{C_1}{C_2} [V_{i1}(z) - V_{i2}(z)] - \frac{C_{p1}}{C_2} V_{i1}(z) \right] \times \frac{z^{-1}}{1 - z^{-1}}$$

# Effects of parasitic Cs

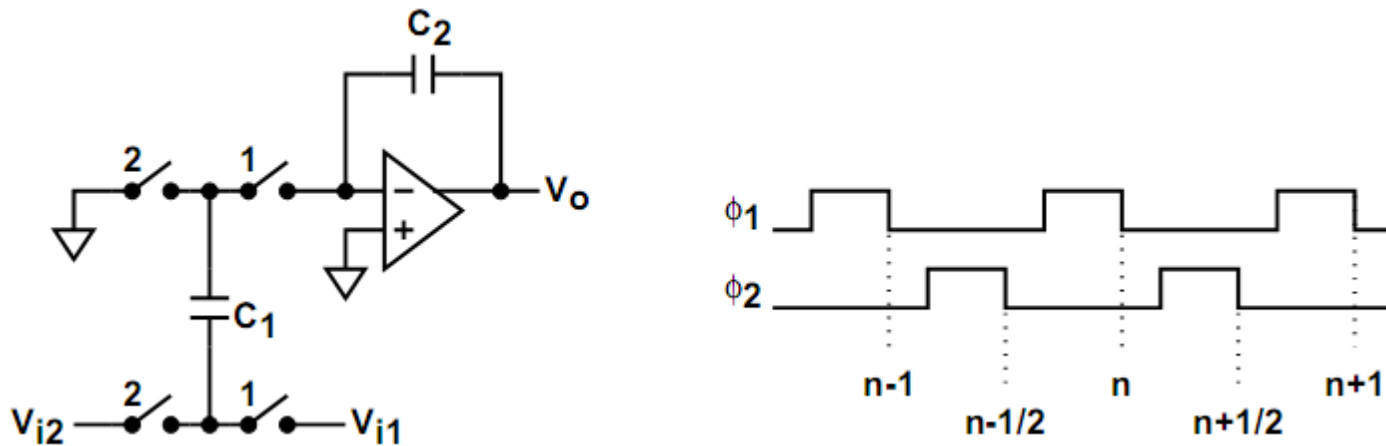
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- Among the parasitic capacitors, only  $C_{p1}$  contribute charge to  $C_2$  if  $A = \infty$ .
- Consider a finite value of  $A$ , then  $V_o = -A \cdot V_a$ , and

$$\begin{aligned}
 & C_1[V_{i1}(n) - V_{i2}(n)] + C_2[V_a(n) - V_o(n)] + C_{p1}V_{i1} + C_{p3}V_a(n) \\
 &= (C_1 + C_{p1} + C_{p3}) V_a(n + 1) + C_2[V_a(n + 1) - V_o(n + 1)] \\
 \Rightarrow \quad V_o(z) &= \frac{\left[ -\frac{C_1}{C_2}[V_{i1}(z) - V_{i2}(z)] - \frac{C_{p1}}{C_2}V_{i1}(z) \right] \times z^{-1}}{1 + \frac{1}{A} \left( 1 + \frac{C_1}{C_2} + \frac{C_{p1}}{C_2} + \frac{C_{p3}}{C_2} \right) - z^{-1} \left[ 1 + \frac{1}{A} \left( 1 + \frac{C_{p3}}{C_2} \right) \right]}
 \end{aligned}$$

- Must keep  $C_{p1} \ll C_1$  and  $C_{p1,p3} \ll C_2$ .
  - Connect the top plates of the capacitors to the opamp's input.
  - Let the bottom plates of the capacitors always be driven.

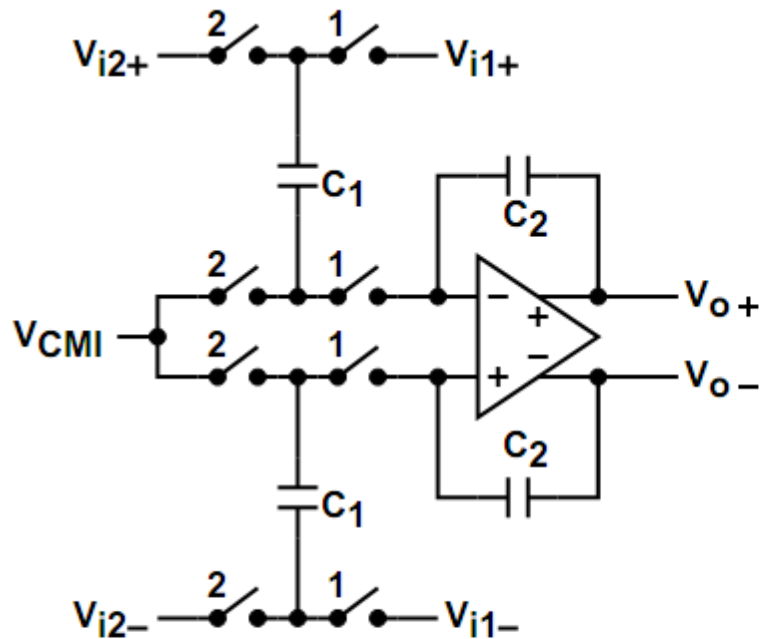
# Parasitic-insensitive SC integrator



$$V_o(z) = \frac{\frac{C_1}{C_2} [-V_{i1} + z^{-1}V_{i2}]}{1 + \frac{1}{A} \left( 1 + \frac{C_1}{C_2} + \frac{C_{p1}}{C_2} + \frac{C_{p3}}{C_2} \right) - z^{-1} \left[ 1 + \frac{1}{A} \left( 1 + \frac{C_{p3}}{C_2} \right) \right]}$$

- Insensitive to parasitics if  $A \rightarrow \infty$ .
- The two inputs have different delays.

# Fully-differential SC integrator



$$V_{i1} = V_{i1+} - V_{i1-}$$

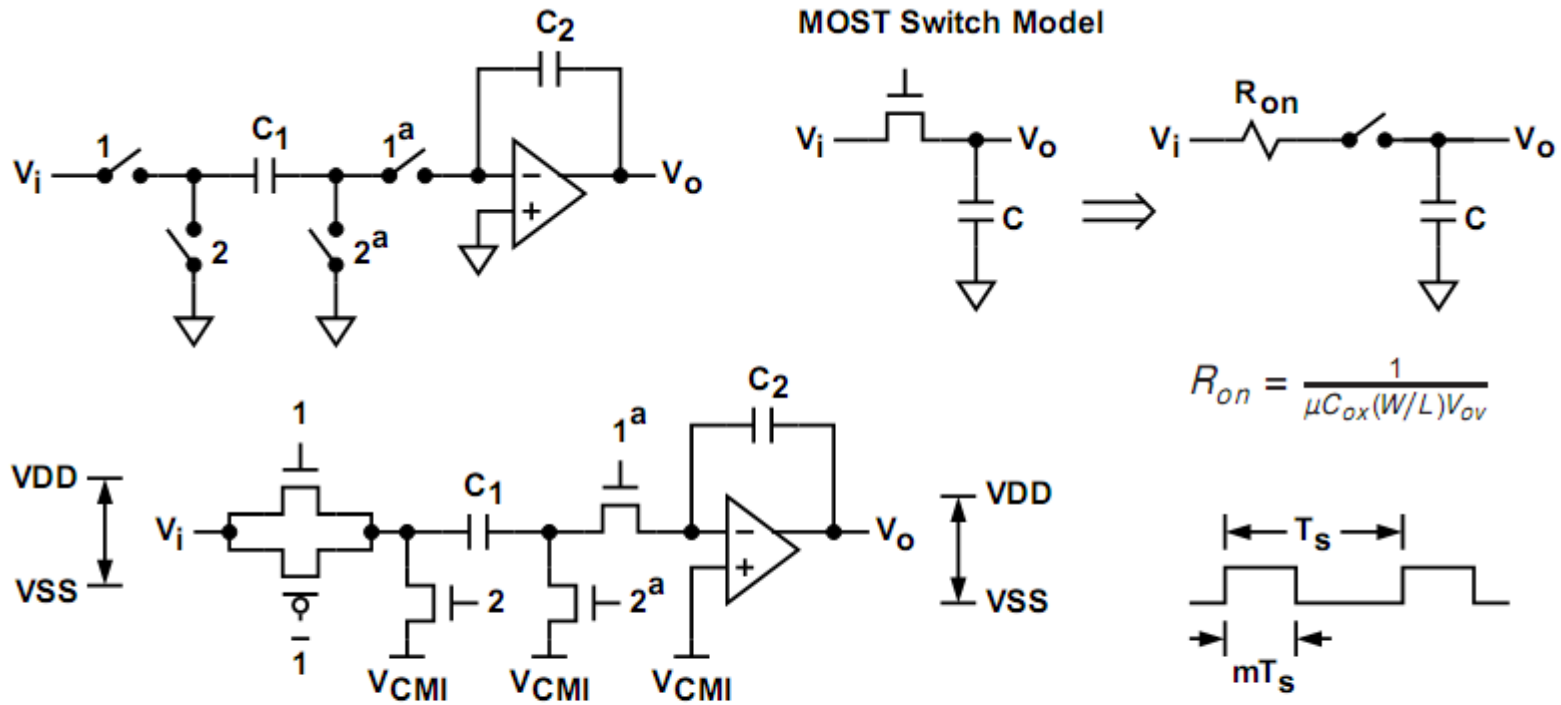
$$V_{i2} = V_{i2+} - V_{i2-}$$

$$V_o = V_{o+} - V_{o-}$$

$$V_o(z) = \frac{C_1}{C_2} \times \left[ -\frac{1}{1-z^{-1}} \cdot V_{i1} + \frac{z^{-1}}{1-z^{-1}} \cdot V_{i2} \right]$$

- $V_{CMI}$  and  $V_{CMO}$  can be different.

# MOSFET switch



For good settling, want

$$mT_s > 5R_{on}C = \frac{5C}{\mu C_{ox}(W/L)V_{ov}}$$

# MOSFET switch

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- When turning off the switch, the switching error is

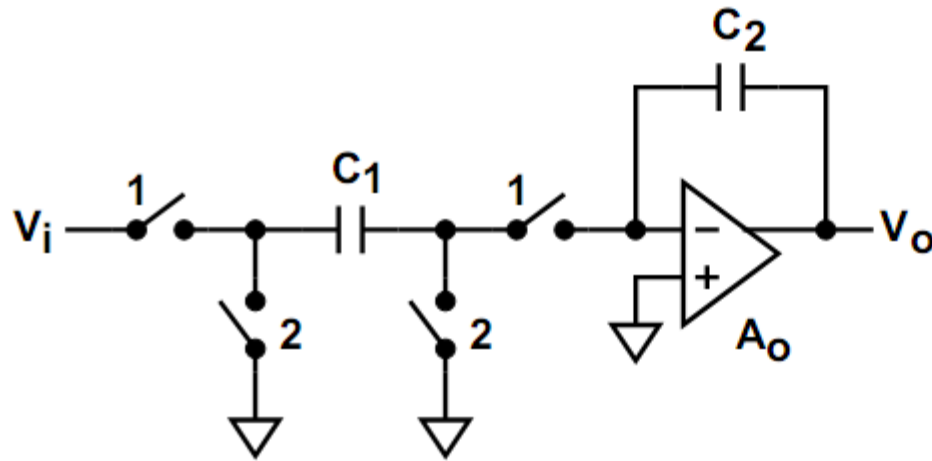
$$\Delta V = \frac{\alpha Q_{CH}}{C} = \frac{\alpha W L C_{ox} V_{ov}}{C}$$

The maximum clock rate is

$$f_s < \frac{m}{\alpha} \cdot \frac{\mu \Delta V}{5L^2}$$

- Realize switches connected to  $V_{SS}$  or near  $V_{SS}$  with nMOSTs.
- Realize switches connected to  $V_{DD}$  or near  $V_{DD}$  with pMOSTs.
- Turn off the switches near the virtual ground node of the opamps first.
- The thermal noise is proportional to  $kT/C$ .
- There are also noises from the power supplies.

# Effects of opamp finite DC gain



If  $A_o = \infty$ , then

$$V_o(n) = -kV_i(n) + V_o(n-1)$$

$$H(z) = -\frac{k}{1-z^{-1}}$$

$$k = \frac{C_1}{C_2}$$

If  $A_o = 1/\mu$  is finite, then

$$V_o(n) = -k\alpha V_i(n) + \beta V_o(n-1) \quad H(z) = -\frac{k\alpha}{1-\beta z^{-1}}$$

$$\alpha = \frac{1}{1+(1+k)\mu} \approx 1 - (1+k)\mu = 1 + \Delta\alpha \quad \Delta\alpha = -(1+k)\mu \ll 1$$

$$\beta = \frac{1+\mu}{1+(1+k)\mu} \approx 1 - k\mu = 1 + \Delta\beta \quad \Delta\beta = -k\mu \ll 1$$

# Effects of opamp finite DC gain

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The transfer function  $H(z)$  in s-domain is

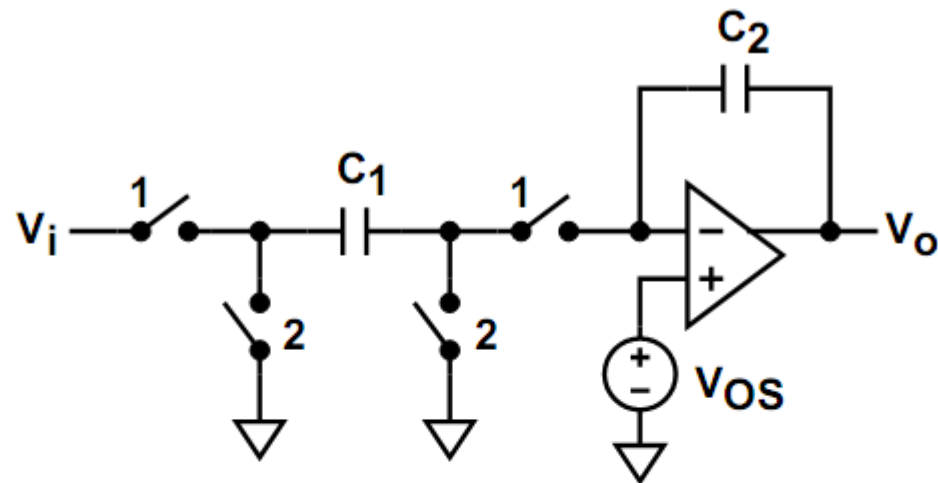
$$H(e^{j\omega T_s}) \approx -\frac{k}{1-z^{-1}} \Big|_{z=e^{j\omega T_s}} \times [1 + m(\omega)] e^{j\theta(\omega)}$$
$$m(\omega) \approx \Delta\alpha - \frac{\Delta\beta}{2} \approx -\left(1 + \frac{1C_1}{2C_2}\right) \cdot \frac{1}{A_o}$$
$$\theta(\omega) \approx -\frac{\Delta\beta}{2} \cdot \frac{1}{\tan(\omega T_s/2)} \approx \frac{1}{2} \cdot \frac{C_1}{C_2} \cdot \frac{1}{A_o} \cdot \frac{1}{\tan(\omega T_s/2)} \approx \frac{C_1}{C_2} \cdot \frac{1}{A_o} \cdot \frac{1}{\omega T_s}$$

- At the unit-gain frequency  $\omega_i$ , where  $|H(e^{j\omega_i T_s})| = 1$ , we have

$$-m(\omega_i) \approx \theta(\omega_i) \approx 1/A_o \quad \text{if} \quad \omega_i T_s/2 \ll 1$$

- In most applications, the magnitude error  $m(\omega)$  has negligible effect, but the phase error  $\theta(\omega)$  can be detrimental in narrowband (high-Q) filters.

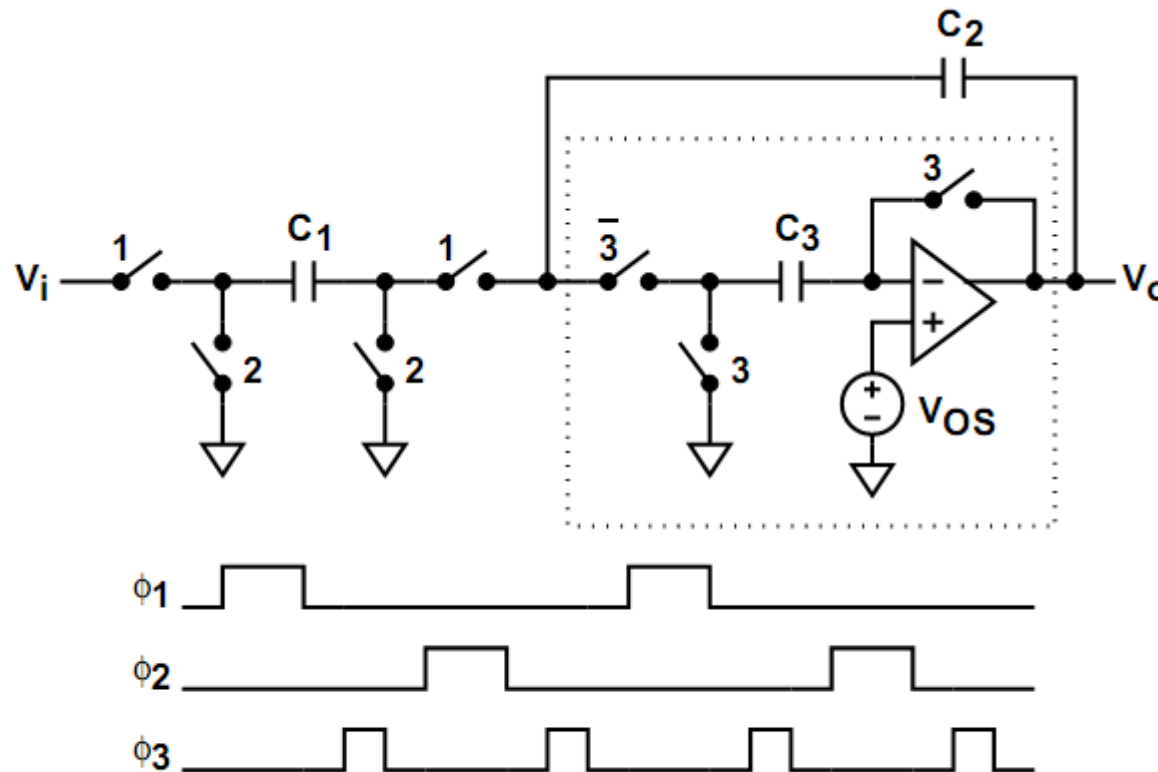
# Effects of opamp DC offset



$$V_o(z) = -\frac{C_1}{C_2} \frac{1}{1-z^{-1}} \cdot V_i(z) + \frac{C_1}{C_2} \frac{1}{1-z^{-1}} \cdot V_{OS} + V_{OS}$$

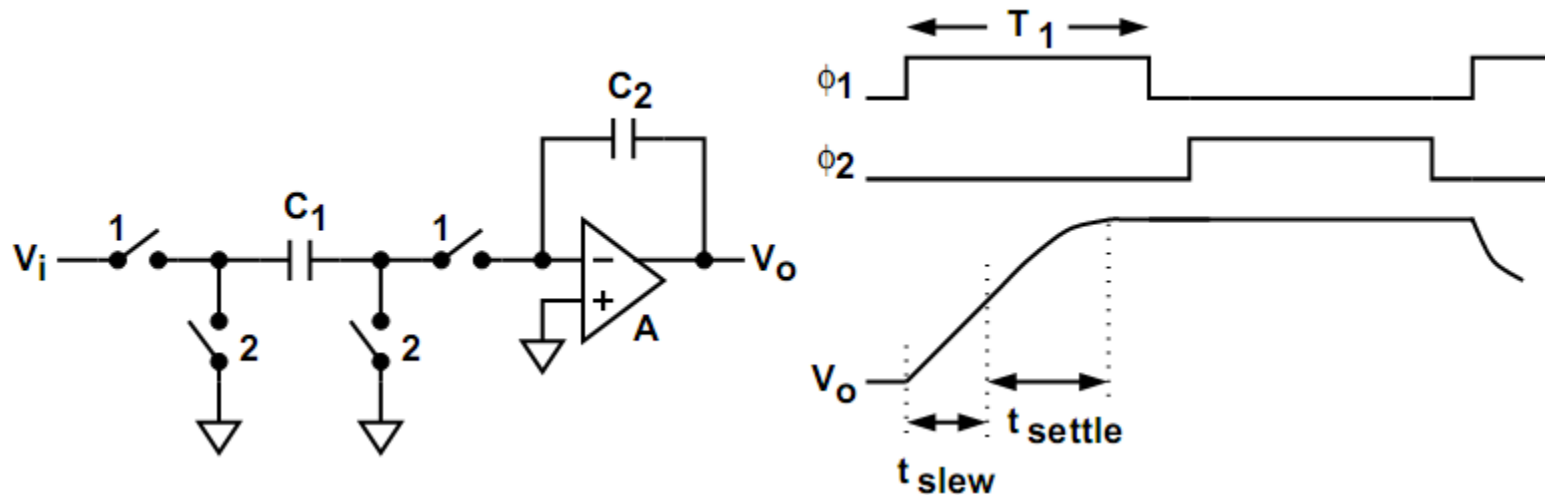
- The  $V_{OS}$  to  $V_o$  transfer function is also an integration.
- When the entire filter is considered, the  $V_{OS}$  may cause finite dc level shift in this and other integrators.

# Auto-zeroing scheme



- During the  $\phi_3$  auto-zeroing mode, opamp's offset voltage is stored in  $C_3$ .

# Effect of opamp finite settling time

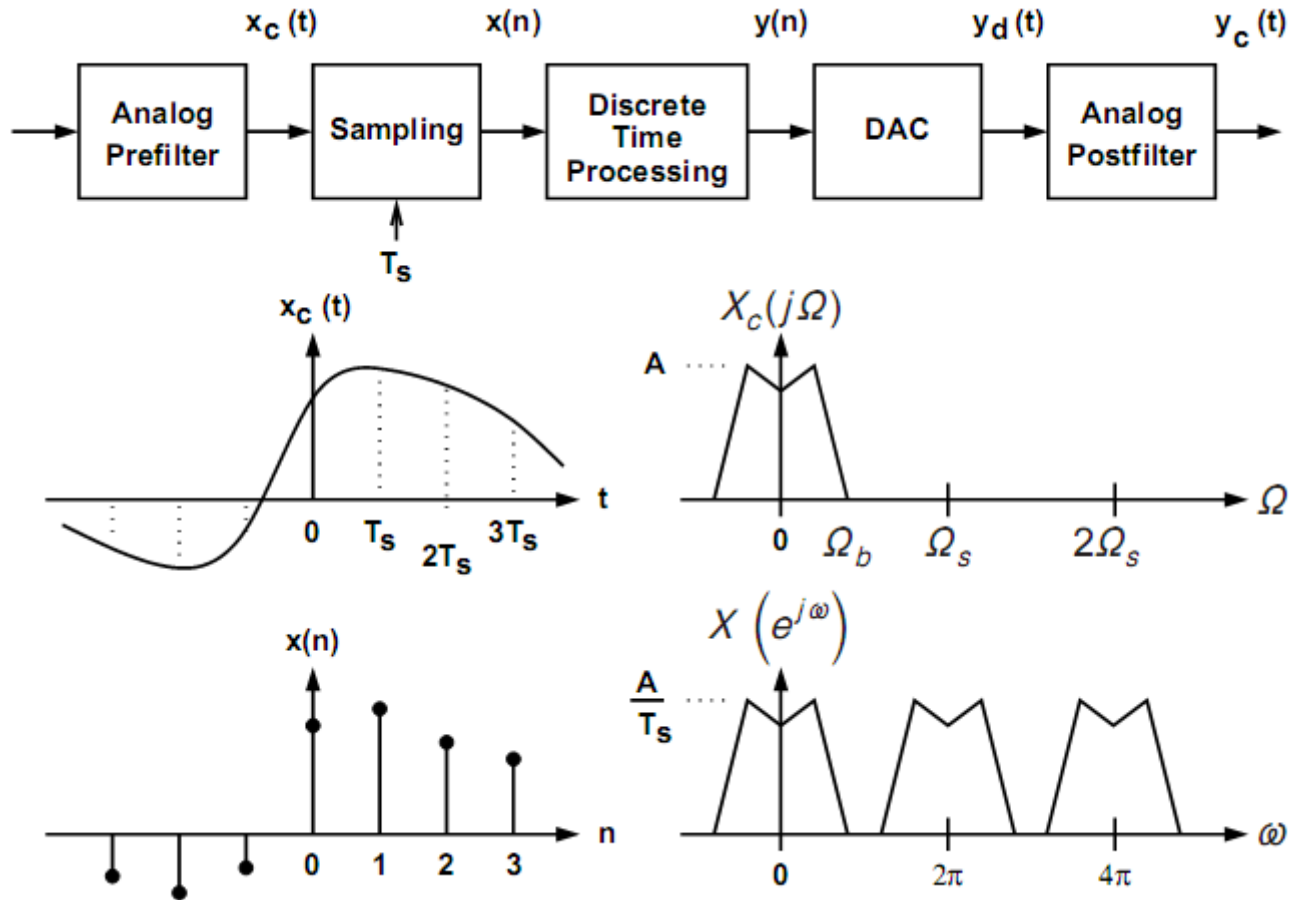


- Let  $t_{slew} = 0$ ,  $A(s) = \omega_u/s$ ,  $T_1 = T_s/2$ ,  $\omega_i$  is the unit-gain frequency of the integrator, and  $\omega_i T_s \ll 1$ . At  $\omega = \omega_i$ , the magnitude error and phase error of the integrator are

$$m(\omega_i) \approx \theta(\omega_i) \approx -\omega_i T_s e^{-\omega_u T_s / 2}$$

- Want  $\omega_u \geq 5 \cdot \omega_s$ . However, to avoid unnecessary noise aliasing,  $\omega_u$  should not be too much larger than necessary.

# Discrete-time signal processing



# Continuous-time signal

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The Laplace transform and the continuous-time Fourier transform (CTFT) are

$$X_c(s) = \int_{-\infty}^{\infty} x_c(t)e^{-st} dt \quad X_c(j\Omega) = \int_{-\infty}^{\infty} x_c(t)e^{-j\Omega t} dt$$

If the region of convergence of  $X_c(s)$  includes the imaginary axis, then

$$X_c(j\Omega) = X_c(s)|_{s=j\Omega}$$

**Sampling Theorem:** To avoid aliasing, want

$$\Omega_s > 2\Omega_b \quad \Omega_s = 2\pi f_s = \frac{2\pi}{T_s}$$

- $\Omega_b$  is the bandwidth of  $x_c(t)$ ,  $\Omega_s$  is the sampling frequency, and  $2\Omega_b$  is called the *Nyquist rate*.

# Discrete-time signal

---

In discrete-time domain, the z transform is

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

The discrete-time Fourier transform (DTFT) is

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x(n)e^{-j\omega n}$$

If the region of convergence of  $X(z)$  includes the unit circle, then

$$X(e^{j\omega}) = X(z)|_{z=e^{j\omega}}$$

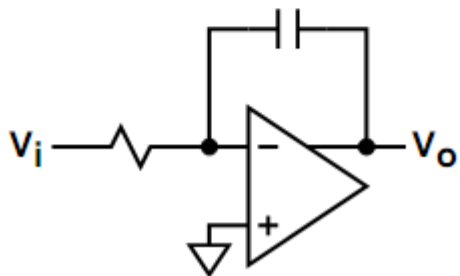
# s-to-z transformation

Want to approximate  $H_c(s)$  with  $H(z)$ .

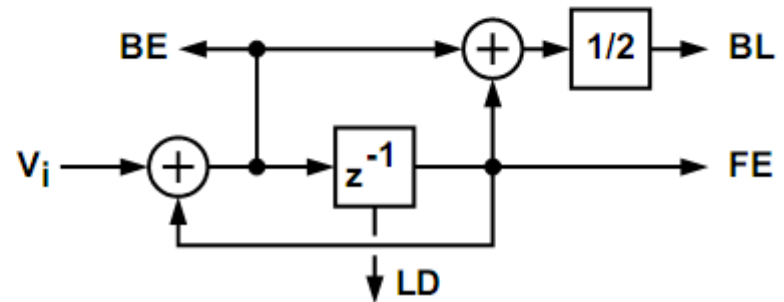
$$z = e^{sT_s} \quad s = \frac{1}{T_s} \cdot \ln z \quad \Rightarrow \quad H(z) = H_c(s)|_{s=(1/T_s)\ln z} \approx H_c(s)|_{s=T(z)}$$

Transformation error of an Integrator can be written as

$$H_c(s) = \frac{1}{s} = \frac{1}{j\Omega} \quad \Rightarrow \quad H(z)|_{e^{j\Omega T_s} = z} = \frac{1}{j\Omega} \cdot [1 - e^{-j\Omega T_s}] \cdot e^{j\phi(\Omega)}$$



s to z  
 $\Rightarrow$



# s-to-z transformation

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Backward Euler (BE) Transformation

$$s = \frac{1}{T_s} \cdot (1 - z^{-1}) \quad \Rightarrow \quad \frac{1}{s} = T_s \cdot \frac{1}{1 - z^{-1}} \quad \epsilon = 1 - \frac{\Omega T_s / 2}{\sin(\Omega T_s / 2)} \quad \phi = +\frac{\Omega T_s}{2}$$

Forward Euler (FE) Transformation

$$s = \frac{1}{T_s} \cdot \frac{1 - z^{-1}}{z^{-1}} \quad \Rightarrow \quad \frac{1}{s} = T_s \cdot \frac{z^{-1}}{1 - z^{-1}} \quad \epsilon = 1 - \frac{\Omega T_s / 2}{\sin(\Omega T_s / 2)} \quad \phi = -\frac{\Omega T_s}{2}$$

Lossless Discrete (LD) Transformation

$$s = \frac{1}{T_s} \cdot \frac{1 - z^{-1}}{z^{-1/2}} \quad \Rightarrow \quad \frac{1}{s} = T_s \cdot \frac{z^{-1/2}}{1 - z^{-1}} \quad \epsilon = 1 - \frac{\Omega T_s / 2}{\sin(\Omega T_s / 2)} \quad \phi = 0$$

# s-to-z transformation

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The transformation is

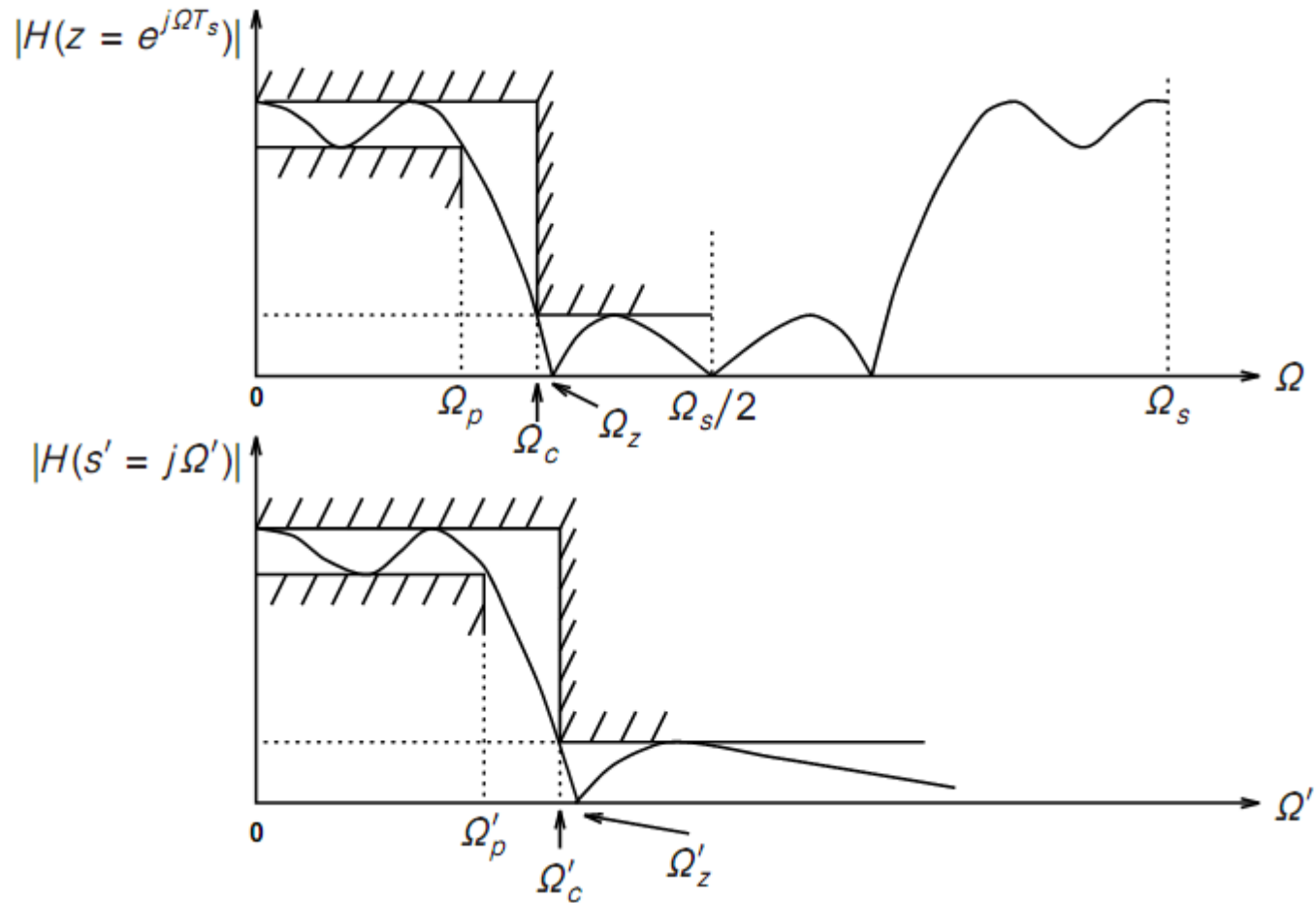
$$s = \frac{2}{T_s} \cdot \frac{1 - z^{-1}}{1 + z^{-1}} \quad \Rightarrow \quad \frac{1}{s} = \frac{T_s}{2} \cdot \frac{1 + z^{-1}}{1 - z^{-1}} \quad \epsilon = 1 - \frac{\Omega T_s / 2}{\tan(\Omega T_s / 2)} \quad \phi = 0$$

let  $z = e^{j\omega}$ , then

$$s = \frac{2}{T_s} \cdot \frac{e^{j\omega} - 1}{e^{j\omega} + 1} = \frac{2}{T_s} \cdot j \tan\left(\frac{\omega}{2}\right) = j\Omega \quad \Omega = \frac{2}{T_s} \tan\left(\frac{\omega}{2}\right)$$

- The unit circle in the z-plane is mapped to the  $j\Omega$  axis in the s-plane.

# Bilinear transformation



# Bilinear transformation

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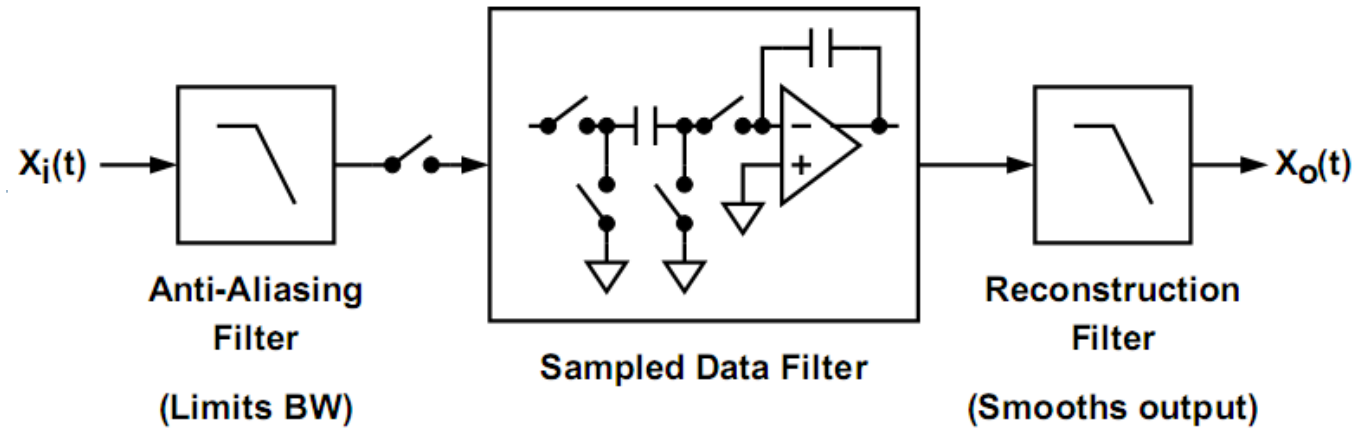
- Prewarp the filter specifications from  $\Omega$  to  $\Omega'$ .

$$\Omega'_p = \frac{2}{T_s} \tan \frac{\Omega_p T_s}{2} \quad \Omega'_c = \frac{2}{T_s} \tan \frac{\Omega_c T_s}{2} \quad \Omega'_z = \frac{2}{T_s} \tan \frac{\Omega_z T_s}{2}$$

- Find  $H_c(s')$ .
- The  $H(z)$  is obtained by

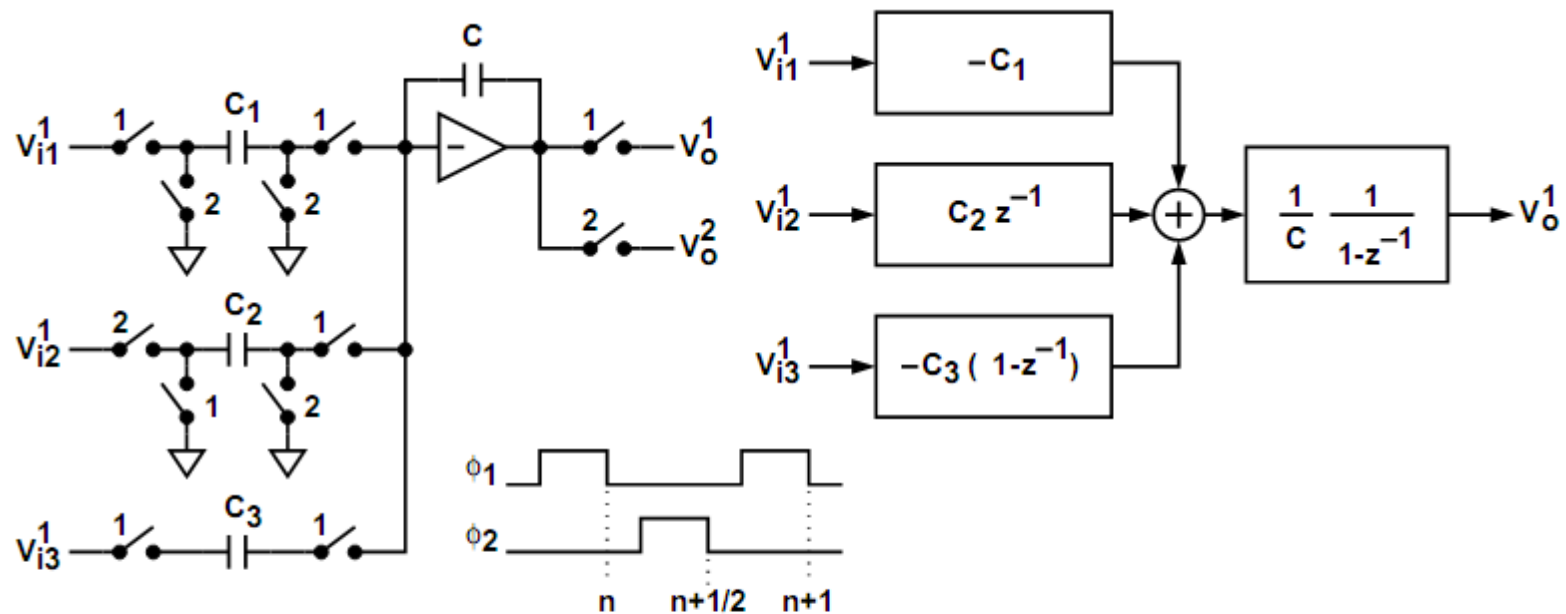
$$H(z) = H_c \left( s' = \frac{2}{T_s} \cdot \frac{1 - z^{-1}}{1 + z^{-1}} \right)$$

# SC filter system



- Discrete-time (or sampled-data) analog filters.
- Filters consist of analog switches, capacitors and opamps.
- Filter response is determined by ratios of capacitance.
- Switched-C “resistor” cannot be the only feedback around an opamp. Since the path is not continuous, it won’t stabilize the opamp.
- No floating node. Otherwise charge can accumulate.
- Capacitor bottom plate must always be driven from a low impedance (voltage sources or ground).
- Connect non-inverting opamp input to a dc bias. Otherwise response is sensitive to parasitic capacitances.

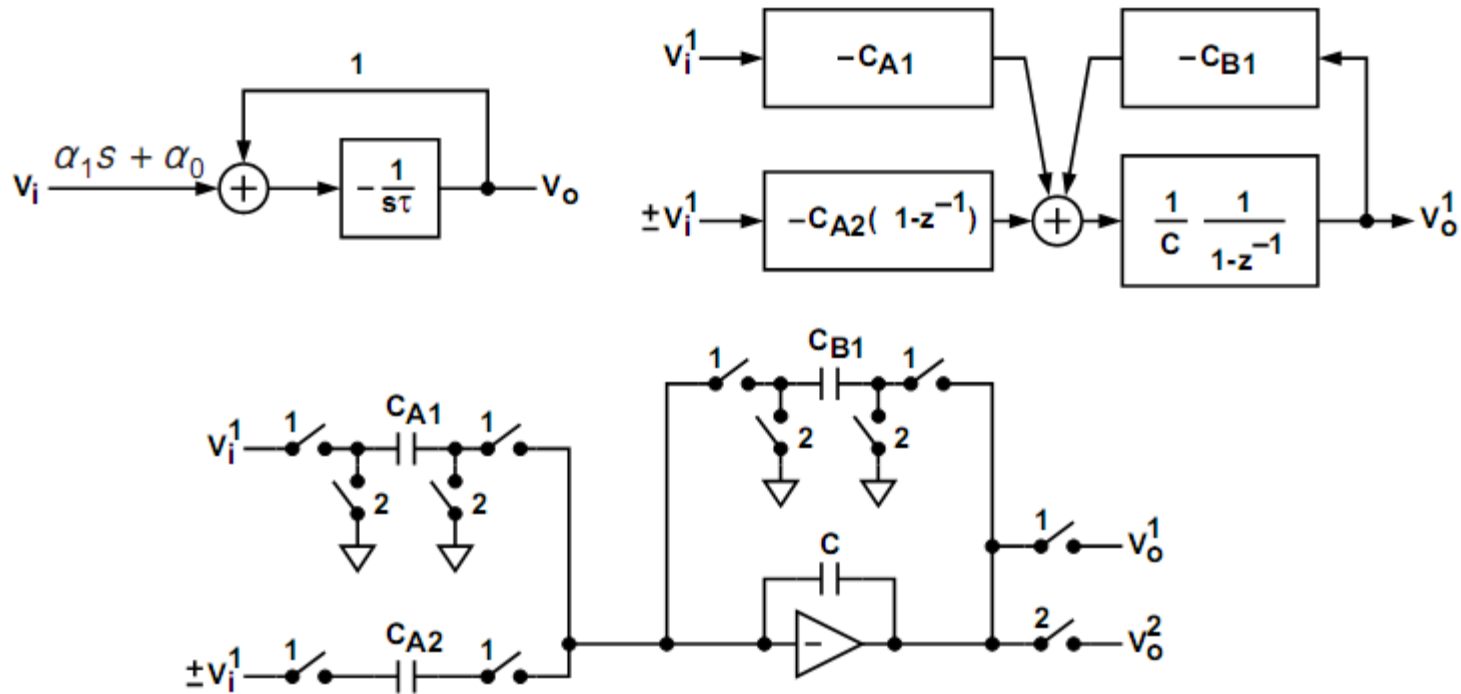
# Active SC integrator



$$V_o^1 = \frac{1}{C(1-z^{-1})} \cdot [-C_1 V_{i1}^1 + C_2 z^{-1} V_{i2}^1 - C_3 (1-z^{-1}) V_{i3}^1]$$

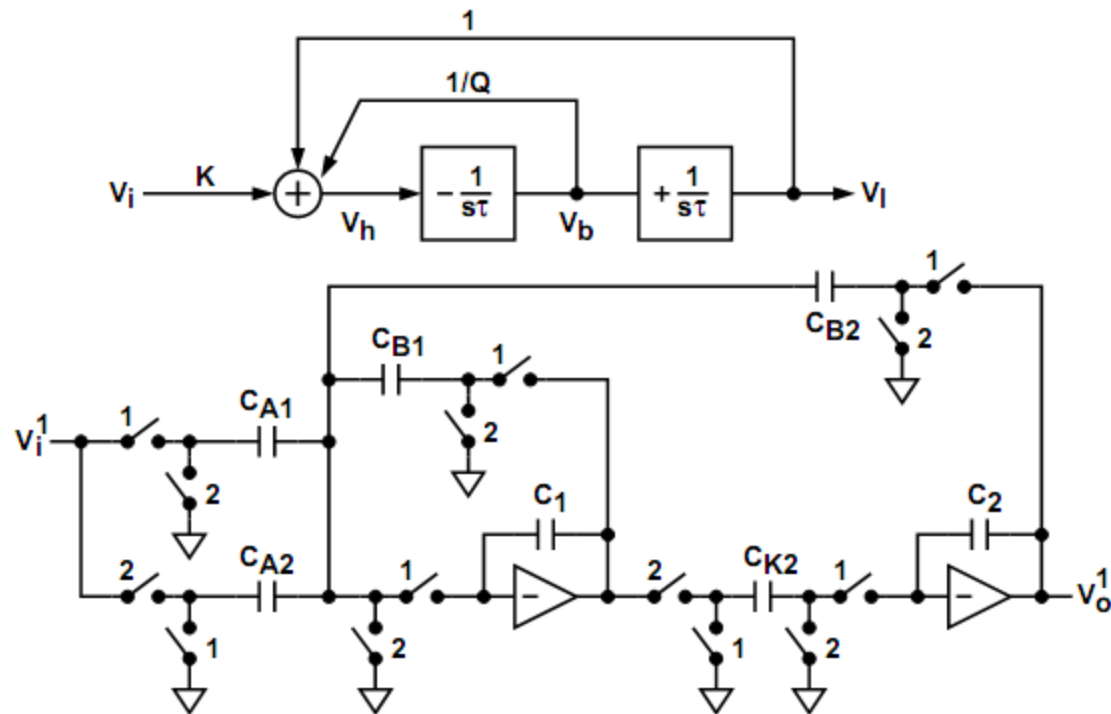
$$V_o^2 = V_o^1 \cdot z^{-1/2}$$

# SC 1<sup>st</sup>-order filter



$$\frac{V_o(s)}{V_i(s)} = -\frac{\alpha_1 s + \alpha_0}{sT + 1} \quad \frac{V_o^1}{V_i^1} = -\frac{C_{A1} \pm C_{A2}(1 - z^{-1})}{C_{B1} + C(1 - z^{-1})} = -\frac{\left(\frac{C_{A1}}{C} \pm \frac{C_{A2}}{C}\right) \mp \frac{C_{A2}}{C} z^{-1}}{\left(\frac{C_{B1}}{C} + 1\right) - z^{-1}}$$

# SC 2<sup>nd</sup>-order filter



$$\frac{V_o^1}{V_i^1} = \frac{\left(\frac{C_{A1} C_{K2}}{C_1 C_2}\right) z^{-1} - \left(\frac{C_{A2} C_{K2}}{C_1 C_2}\right) z^{-2}}{\left(\frac{C_{B1}}{C_1} + 1\right) + \left(\frac{C_{B2}}{C_1} \cdot \frac{C_{K2}}{C_2} - \frac{C_{B1}}{C_1} - 2\right) z^{-1} + z^{-2}}$$

# SC 2<sup>nd</sup>-order filter

